

Discipline :- ELECTRICAL	Semester:- 5 th	Name of the Teaching Faculty:-BISWANATH PRATAP SINGH
ENTREPRENEURSHIP and MANAGEMENT & SMART TECHNOLOGY	No of Days/per Week Class Allotted :-04	Semester From:- <u>14.07.2025</u> To:- <u>15.11.2025</u> No of Weeks:- 18
Week	Class Day	Theory
1 st	1 st	1. Entrepreneurship Concept / Meaning of Entrepreneurship ,
	2 nd	Need of Entrepreneurship , Characteristics
	3 rd	Quality and Types of Entrepreneur, Functions,
	4 th	Barriers of entrepreneurship
2 nd	1 st	Entrepreneur Vs Manager
	2 nd	Forms of Business Ownership ; Sole proprietorship, partnership forms and others
	3 rd	Types of industries, Concept of start-ups
	4 th	Entrepreneurial support agencies at National , State , District Level (sources): DIC , NSIC, OSIC, SIDBI, NABARD , Commercial Banks , KVIC etc
3 rd	1 st	Technology business incubators (TBI) and Science and Technology Entrepreneur Parks
	2 nd	2. Market Survey and Opportunity Identification (Business Planning) Business planning
	3 rd	SSI, Ancillary Units , Tiny Units , Service sector Units
	4 th	Time schedule plan , Agencies to be contacted for project Implementation
4 th	1 st	Assessment of Demand and Supply
	2 nd	Potential areas of Growth
	3 rd	Identifying Business Opportunity
	4 th	Final product selection
5 th	1 st	3. Project report Preparation Preliminary project report
	2 nd	Detailed project report
	3 rd	Techno economic feasibility
	4 th	Project viability
6 th	1 st	4. Management Principles Definitions of management
	2 nd	Principles of management
	3 rd	Functions of management (planning, organizing staffing, directing and controlling etc.)
	4 th	Level of Management in an Organisation
7 th	1 st	5. Functional Areas of management a) Production management->Functions , activities , Productivity
	2 nd	Quality control , Production planning and control
	3 rd	b) Inventory Management

		Need for Inventory management
	4 th	Model/ Techniques of inventory management
8 th	1 st	c)Financial management Functions of financial management , management of working capital, Costing (only concept) ,Break even analysis
	2 nd	Brief idea about accounting Terminologies: Book Keeping , Journal entry ,Petty Cash book , P & L Accounts, Balance Sheets (only concepts)
	3 rd	d)Marketing Management Concept of Marketing and Marketing Management Marketing Techniques (only concept)
	4 th	Concept of 4P s (price ,place ,product ,promotion)
9 th	1 st	e)Human Resource Management Function of Personnel Management, Man power planning ,
	2 nd	Recruitment ,Sources of manpower ,Selection of manpower , Selection process , Method of Testing ,
	3 rd	Methods of Training & Development , Payment of Wages
	4 th	6.Leadership and Motivation a)Leadership Defination and Need/ Importance
10 th	1 st	Qualities and Functions of a leader
	2 nd	Manager Vs Leader
	3 rd	Style of leadership (Autocratic , Democratic , Participative)
	4 th	b)Motivation Defination and Characteristics, Importance of motivation
11 th	1 st	Factors affecting motivation
	2 nd	Theories of motivation (Maslaw)
	3 rd	Methods of improving Motivation
	4 th	Importance of Communication in Business
12 th	1 st	7.Work Culture , TQM & Safety Types and Barriers of Communication
	2 nd	Human relationship and Performance in Organization
	3 rd	Relation with Peers , Superiors and Subordinates
	4 th	TQM concepts: Quality policy , Quality Management , Quality system
13 th	1 st	Accidents and safety , causes and preventive measures
	2 nd	General safety Rules, Personal Protection Equipment (PPE)
	3 rd	8.Legislation Intellectual Property Rights (IPR)
	4 th	Patents, Trademarks, Copyrights
14 th	1 st	Features of factories Act 1948with amendment(only salient point)
	2 nd	Features of Payment of Wages Act 1936(only salient point)
	3 rd	9.Smart Technology

15 th		Concept of IOT ,How IOT works
	4 th	Components of IOT
	1 st	Characteristics of IOT ,Categories of IOT
	2 nd	Application of IOT – Smart cities ,Smart transportation
	3 rd	Smart Home , Smart Healthcare Smart industry
16 th	4 th	Smart Agriculture, Smart Energy Managementetc
	1 st	EXTRA CLASSES
	2 nd	EXTRA CLASSES
	3 rd	EXTRA CLASSES
	4 th	EXTRA CLASSES
17 th	1 st	EXTRA CLASSES
	2 nd	EXTRA CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	DOUBT CLEARING CLASSES
	1 st	DOUBT CLEARING CLASSES
18 th	2 nd	DOUBT CLEARING CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	DOUBT CLEARING CLASSES

13/12
11/11/25
Teaching Faculty

10/12/25
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11/07/2028
Academic Coordinator

Discipline:- Electrical Engineering	Semester:- 5th	Name of the teaching faculty:-PRABHAT RASHIMI MALLIK
Subject:- Energy conversion -II	No. of days/ per week class allotted:-4	Semester from:- <u>14.07.2025</u> To:- <u>15.11.2025</u> No. of weeks:18
Week	Class day	Theory
1 st	1st	1. ALTERNATOR: 1.1. Types of alternator and their constructional features
	2nd	1.2. Basic working principle of alternator and the relation between speed and frequency
	3rd	1.3. Terminology in armature winding and expressions for winding factors (Pitch factor, Distribution factor).
	4th	1.4. Explain harmonics, its causes and impact on winding factor.
2 nd	1st	1.5. E.M.F equation of alternator. (Solve numerical problems).
	2nd	1.6. Explain Armature reaction and its effect on emf at different power factor of load.
	3rd	1.6. Explain Armature reaction and its effect on emf at different power factor of load.
	4th	1.7. The vector diagram of loaded alternator. (Solve numerical problems)
3rd	1st	1.7. The vector diagram of loaded alternator. (Solve numerical problems)
	2nd	1.8. Testing of alternator (Solve numerical problems) 1.8.1. Open circuit test.
	3rd	1.8.2. Short circuit test
	4th	1.9. Determination of voltage regulation of Alternator by direct loading and synchronous impedance method. (Solve numerical problems)
4th	1st	1.10. Parallel operation of alternator using synchro-scope and dark & bright lamp method
	2nd	1.11. Explain distribution of load by parallel connected alternators.
	3rd	2. SYNCHRONOUS MOTOR: 2.1. Constructional feature of Synchronous Motor.
	4th	2.2. Principles of operation, concept of load angle
5th	1st	2.3. Derive torque, power developed.
	2nd	2.4. Effect of varying load with constant excitation
	3rd	2.5. Effect of varying excitation with constant load. 2.6. Power angle characteristics of cylindrical rotor motor
	4th	2.7. Explain effect of excitation on Armature current and power factor. 2.8. Hunting in Synchronous Motor
6th	1st	2.9. Function of Damper Bars in synchronous motor and generator. 2.10. Describe method of starting of Synchronous motor.
	2nd	2.10. Describe method of starting of Synchronous motor 2.11. State application of synchronous moto

7th	3rd	3. THREE PHASE INDUCTION MOTOR: 3.1. Production of rotating magnetic field.
	4th	3.2. Constructional feature of Squirrel cage and Slip ring induction motors.
	1st	3.3. Working principles of operation of 3-phase Induction motor..
	2nd	3.4. Define slip speed, slip and establish the relation of slip with rotor quantities
8th	3rd	3.5. Derive expression for torque during starting and running conditions and derive conditions for maximum torque. (solve numerical problems)
	4th	3.5. Derive expression for torque during starting and running conditions and derive conditions for maximum torque. (solve numerical problems)
	1st	3.6. Torque-slip characteristics
	2nd	3.7. Derive relation between full load torque and starting torque etc. (solve numerical problems)
9th	3rd	3.8. Establish the relations between Rotor Copper loss, Rotor output and Gross Torque and relationship of slip with rotor copper loss. (solve numerical problems)
	4th	3.9. Methods of starting and different types of starters used for three phase Induction motor.
	1st	3.10. Explain speed control by Voltage Control, Rotor resistance control, Pole changing, frequency control methods
	2nd	3.11. Plugging as applicable to three phase induction motor
10th	3rd	3.12. Describe different types of motor enclosures.
	4th	3.13. Explain principle of Induction Generator and state its applications
	1st	4. SINGLE PHASE INDUCTION MOTOR: 4.1. Explain Ferrari's principle.
	2nd	4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase induction motor.
11th	3rd	4.3. Explain Working principle, Torque speed characteristics, performance characteristics and application of following single phase motors 4.3.1. Split phase motor.
	4th	4.3.2. Capacitor Start motor.
	1st	4.3.3. Capacitor start, capacitor run motor

12th	2nd	4.3.4. Permanent capacitor type motor.
	3rd	4.3.5. Shaded pole motor
	4th	4.4. Explain the method to change the direction of rotation of above motors.
	1st	5. COMMUTATOR MOTORS:
12th	2nd	5.1. Construction, working principle of single phase series motor
	3rd	5.1. Running characteristic and application of single phase series motor
	4th	5.2. Construction of Universal motors
	4th	5.2. working principle and application of Universal motors
13th	1st	5.3. Working principle of Repulsion start Motor
	2nd	5.3. Working principle of Repulsion start Induction run motor, Repulsion Induction motor.
	3rd	6. SPECIAL ELECTRICAL MACHINE:
	4th	6.1. Principle of Stepper motor.
14th	1st	6.2. Classification of Stepper motor.
	1st	6.3. Principle of variable reluctant stepper motor.
	2nd	6.4. Principle of Permanent magnet stepper motor
	3rd	6.5. Principle of hybrid stepper motor
15th	4th	6.6. Applications of Stepper motor.
	4th	7. THREE PHASE TRANSFORMERS:
	1st	7.1. Explain Grouping of winding, Advantages.
	2nd	7.2. Explain parallel operation of the three phase transformers.
16th	3rd	7.3. Explain tap changer (On load tap changing.
	4th	7.4. Explain Off load tap changing
	4th	7.4. Maintenance Schedule of Power Transformers.
	1st	DOUBT CLEARING CLASSES
17th	2nd	DOUBT CLEARING CLASSES
	3rd	DOUBT CLEARING CLASSES
	4th	DOUBT CLEARING CLASSES
	1st	Problem Solving Classes
18th	2nd	DOUBT CLEARING CLASSES
	3rd	Problem Solving Classes
	4th	EXTRA CLASSES
	1st	EXTRA CLASSES
	2nd	EXTRA CLASSES

	3 rd	EXTRA CLASSES
	4 th	EXTRA CLASSES


 11/07/2025
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 11/07/2025
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 11/07/2025
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Discipline: ELECTRICAL ENGINEERING	Semester :5 th	Name of the Teaching Faculty: SOMA DAS
Subject: DE&MP	No. of days/per week class allotted:05	Semester From date : <u>02.08.2025</u> To:- <u>15.11.2025</u>
Week	Class Day	Theory Topics
1 ST	1 ST	Binary, Octal, Hexadecimal number systems and compare with Decimal system.
	2 ND	Binary addition, subtraction, Multiplication and Division.
	3 RD	1's complement and 2's complement numbers for a binary number
	4 th	Subtraction of binary numbers in 2's complement method.
	5 th	Use of weighted and Un-weighted codes & write Binary equivalent number for a number in 8421, Excess-3 and Gray Code and vice-versa
2 ND	1 ST	Importance of parity Bit.
	2 ND	Logic Gates: AND, OR, NOT, NAND, NOR and EX-OR gates with truth table. 1.8 Realize
	3 RD	Realize AND, OR, NOT operations using NAND, NOR gates
	4 th	Different postulates and De-Morgan's theorems in Boolean algebra
	5 th	Use Of Boolean Algebra For Simplification Of Logic Expression
3 RD	1 ST	Karnaugh Map For 2,3,4 Variable, Simplification Of SOP And POS Logic Expression Using K-Map.
	2 ND	Give the concept of combinational logic circuits
	3 RD	Half adder circuit and verify its functionality using truth table
	4 th	Realize a Half-adder using NAND gates only and NOR gates only
	5 th	Full adder circuit and explain its operation with truth table
4 TH	1 ST	Realize full-adder using two Half-adders and an OR – gate and write truth table
	2 ND	Full subtractor circuit and explain its operation with truth table.
	3 RD	Operation of 4 X 1 Multiplexers and 1 X 4 demultiplexer
	4 th	Working of Binary-Decimal Encoder & 3 X 8 Decoder
	5 th	Working of Two bit magnitude comparator
5 TH	1 ST	Give the idea of Sequential logic circuits
	2 ND	State the necessity of clock and give the concept of level clocking and edge triggering
	3 RD	Clocked SR flip flop with preset and clear inputs.
	4 th	Construct level clocked JK flip flop using S-R flip-flop and explain with truth table

	5 th	Concept of race around condition and study of master slave JK flip flop.
6 TH	1 ST	Give the truth tables of edge triggered D and T flip flops and draw their symbols.
	2 ND	Applications of flip flops.
	3 RD	Define modulus of a counter 4-bit asynchronous counter
	4 th	4-bit asynchronous counter's timing diagram
	5 th	Asynchronous decade counter
7 TH	1 ST	4-bit synchronous counter.
	2 ND	Distinguish between synchronous and asynchronous counters
	4 th	State the need for a Register and list the four types of registers.
	5 th	WORKING OF PISO, PIPO Register with truth table using flip flop
8 TH	1 ST	Introduction to Microprocessors
	2 ND	Evolution of digital computer, Microprocessors
	3 RD	Basics of CPU and its block diagram
	4 th	Basics of Memory, different types of Memory
	5 th	Buses- Data, Address and Control Bus
9 TH	1 ST	Architecture of Intel 8085A Microprocessor
	2 ND	Description of each block in Architecture
	3 RD	Status Flag concept
	4 th	Status flag with examples
	5 th	Stack, Stack pointer & stack top
10 TH	1 ST	Pin diagram
	2 ND	Grouping of pins
	3 RD	Description of each groups briefly
	4 th	Relation between IO/Memory and read-write operation
	5 th	Reset instruction
11 TH	1 ST	Address and Address-Data instruction
	2 ND	Interrupts
	3 RD	Opcode & Operand
	4 th	one byte, two byte & three byte instruction
	5 th	Differentiate between one byte, two byte & three byte instruction with example.
12 TH	1 ST	Instruction set of 8085
	2 ND	Instruction set of 8085 example
	3 RD	Addressing mode
	4 th	Fetch Cycle, Machine Cycle, Instruction Cycle, T-State
	5 th	Using of Fetch Cycle, Machine Cycle, Instruction Cycle, T-State in Timing Diagram

13 RD	1 ST	Timing Diagram for memory read, memory write
	2 ND	Timing Diagram for I/O read, I/O write
	3 RD	Timing Diagram for 8085 instruction
	4 th	Timing Diagram for 8085 instruction with examples
	5 th	Counter and time delay
14 TH	1 ST	Simple assembly language programming of 8085
	2 ND	Simple assembly language programming of 8085
	3 RD	Introduction to interfacing and support chips
	4 th	Basic Interfacing Concepts
	5 th	Memory mapping & I/O mapping
15 TH	1 ST	Functional block diagram and description of each block of Programmable peripheral interface Intel 8255
	2 ND	Description of each block of Programmable peripheral interface Intel 8255
	3 RD	Application using 8255: Seven segment LED display
	4 th	Application using 8255: Square wave generator
	5 th	Application using 8255: Traffic light Controller

Teaching Faculty

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Academic Coordinator

Discipline:- Electrical Engineering	Semester:- 5th	Name of the teaching faculty:-PRABHAT RASHMI MALLIK
Subject:- Utilization Of Electrical Energy And Traction	No. of days/ per week class allotted:-4	Semester from:- <u>14.07.2025</u> To:- <u>15.11.2025</u> No. of weeks:18
Week	Class day	Theory
1 st	1st	1. ELECTROLYTIC PROCESS 1.1 Definition and Basic principle of Electro Deposition.
	2nd	1.2 Important terms regarding electrolysis
	3rd	1.3 Faradays Laws of Electrolysis. 1.4 Definitions of current efficiency, Energy efficiency
	4th	1.5 Principle of Electro Deposition.
2 nd	1st	1.6 Factors affecting the amount of Electro Deposition
	2nd	1.7 Factors governing the electro deposition.
	3rd	1.8 State simple example of extraction of metals.
	4th	1.9 Application of Electrolysis.
3rd	1st	ELECTRICAL HEATING 2.1. Advantages of electrical heating. 2.2. Explain mode of heat transfer and Stephen's Law.
	2nd	2.3. Discuss principle of Resistance heating. Direct Resistance heating. Indirect Resistance heating
	3rd	2.4. Explain working principle of direct arc furnace and indirect arc furnace.
	4th	2.5. Principle of Induction heating
4th	1st	2.5.1 Working principle of direct core type, vertical core type and indirect core type Induction furnace.
	2nd	2.5.2. Principle of coreless induction furnace and skin effect.
	3rd	2.6. Principle of dielectric heating and its application
	4th	2.7. Principle of Microwave heating and its application.
5th	1st	PRINCIPLES OF ARC WELDING 3.1 Explain principle of arc welding.
	2nd	3.2 Discuss D. C. & A. C. arc phenomena
	3rd	3.3 D.C. & A. C. arc welding plants of single and multi-operation type.
		3.3 D.C. & A. C. arc welding plants of single and multi-operation type.
6th	1st	3.4 Types of arc welding
	2nd	3.5 Explain principles of resistance welding.
	3rd	3.6 Descriptive study of different resistance welding methods.
	4th	3.6 Descriptive study of different resistance welding methods.
7th	1st	4. ILLUMINATION

		4 . 1 Nature of Radiation and its spectrum.
	2nd	4 . 2 Terms used in Illuminations. i. Luminous intensity ii. Lumen iii. Intensity of illumination iv. MHCP v. MSCP vi. MHSCP vii. Brightness viii. Solid angle ix. Luminous efficiency
	3rd	4 . 3 Explain the inverse square law and the cosine law
	4th	4 . 4 Explain polar curves.
8th	1st	4 . 5 Describe light distribution and control. Explain related definitions like maintenance factor and depreciation factors.
	2nd	4 . 6 Design simple lighting schemes and depreciation factor.
	3rd	4. 7 Constructional feature and working of Filament lamps, effect of variation of voltage on working of filament lamps.
	4th	4 . 8 Explain Discharge lamps.
9th	1st	4 . 9 State Basic idea about excitation in gas discharge lamps. 4 . 10 State constructional features and operation of: - Fluorescent lamp. (PL and PLL Lamps)
	2nd	4.11 Sodium Vapor lamp
	3rd	4.12 High Pressure Mercury vapor lamp
	4th	4.13 Neon sign lamp 4.14 High Lumen output & low consumption fluorescent lamp
10th	1st	INDUSTRIAL DRIVES 5 . 1 State group and individual drive.
	2nd	5 . 2 Method of choice of electric drives.
	3rd	5 . 3 Explain starting and running characteristics of DC and AC motor.
	4th	5 . 3 Explain starting and running characteristics of DC and AC motor.
11th	1st	5 . 3 Explain starting and running characteristics of DC and AC motor.
	2nd	5 . 3 Explain starting and running characteristics of DC and AC motor.
	3rd	5 . 4 State Application of : 5.4.1 DC motor
	4th	5.4.2 3-phase induction motor

12th	1st	5.4.3 3-phase synchronous motors
	2nd	5.4.4 Single phase induction ,series motor, universal motor & repulsion motor
	3rd	ELECTRIC TRACTION 6. 1. Explain system of traction
	4th	6. 1. Explain system of traction
13th	1st	6. 2. System of Track electrification
	2nd	6. 2. System of Track electrification
	3rd	6. 3. Running Characteristics of DC and AC traction motor
	4th	6. 3. Running Characteristics of DC and AC traction motor
14th	1st	6. 4. Explain control of motor 6.4.1 Tapped field control
	2nd	6. 4. 2 Rheostatic control
	3rd	. 6.4.3 Series parallel control
	4th	6. 4.4 Multi-unit control
15th	1st	6.4.5 Explain control of Metadyne control
	2nd	6. 5. Explain Braking of the following types. 6.5.1 Regenerative Braking
	3rd	6.5.2 Braking with 1-phase series motor
	4th	6.5.3 Magnetic Braking
16th	1st	DOUBT CLEARING CLASSES
	2 nd	DOUBT CLEARING CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	DOUBT CLEARING CLASSES
17th	1st	DOUBT CLEARING CLASSES
	2 nd	DOUBT CLEARING CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	EXTRA CLASSES
18th	1st	EXTRA CLASSES
	2 nd	EXTRA CLASSES
	3 rd	EXTRA CLASSES
	4 th	EXTRA CLASSES


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Discipline: ELECTRIC AL ENGINEERING	Semester : 5th	Name of the Teaching Faculty: PRATIK DAS & PREETINANDA MISRA
Subject: PE&PLC	No. of days/per week class allotted: 04	Semester From date : 09.09.2025 To:- 15.11.2025
Week	Class Day	Theory Topics
1ST	1ST	Construction, Operation, V-I characteristics & application of power diode, SCR, DIAC, TRIAC, Power MOSFET, GTO & IGBT
	2ND	Two transistor analogy of SCR. Gate characteristics of SCR.
	3RD	Switching characteristic of SCR during turn on and turn off.
	4th	Turn on methods of SCR.
2ND	1ST	Turn off methods of SCR (Line commutation and Forced commutation) - Load Commutation, Resonant pulse commutation
	2ND	Voltage and Current ratings of SCR.
	3RD	Protection of SCR - Over voltage protection, Over current protection, Gate protection
	4th	Firing Circuits- General layout diagram of firing circuit, R firing circuits, R-C firing circuit, UJT pulse trigger circuit
3RD	1ST	Synchronous triggering (Ramp Triggering) Design of Snubber Circuits
	2ND	Controlled rectifiers Techniques (Phase Angle, Extinction Angle control) Single quadrant semi converter
	3RD	Two quadrant full converter and dual Converter Working of single-phase half wave controlled converter with Resistive and R-L loads.
	4th	Understand need of freewheeling diode. Working of single phase fully controlled converter with resistive and R- L loads
4TH	1ST	Working of three-phase half wave controlled converter with Resistive load
	2ND	Working of three phase fully controlled converter with resistive load.
	3RD	Working of single phase AC regulator Working principle of step up & step down chopper.
	4th	Control modes of chopper Operation of chopper in all four quadrants.
5TH	1ST	Classify inverters. Explain the working of series inverter.
	2ND	Explain the working of parallel inverter Explain the working of single-phase bridge inverter.
	3RD	Explain the basic principle of Cyclo-converter.

6 TH	4 th	Explain the working of single-phase step up & step down Cyclo-converter. Applications of Cyclo-converter.
	1 ST	List applications of power electronic circuits. List the factors affecting the speed of DC Motors.
	2 ND	Speed control for DC Shunt motor using converter.
	3 RD	Speed control for DC Shunt motor using chopper. List the factors affecting speed of the AC Motors.
	4 th	Speed control of Induction Motor by using AC voltage regulator.
7 TH	1 ST	Speed control of induction motor by using converters and inverters (V/F control)
	2 ND	Working of UPS with block diagram
	3 RD	Battery charger circuit using SCR with the help of a diagram.
	4 th	Basic Switched mode power supply (SMPS) - explain its working & applications
8 TH	1 ST	Introduction of Programmable Logic Controller(PLC)
	2 ND	Advantages of PLC Different parts of PLC by drawing the Block diagram
	3 RD	purpose of each part of PLC In the Block diagram
	4 th	Different parts of PLC by drawing the Block diagram and purpose of each part of PLC. 5.4 Applications of PLC
9 TH	1 ST	Description of contacts and coils in the following states i) Normally open ii) Normally closed iii) Energized output
	2 ND	iv) latched Output v) branching PLC Instruction set
	3 RD	Ladder diagrams for i) AND gate ii) OR gate and iii) NOT gate. Ladder diagrams for combination circuits using NAND, NOR, AND, OR and NOT
	4 th	Timers-i) T ON ii) T OFF and iii) Retentive timer
10 TH	1 ST	Counters-CTU, CTD Ladder diagrams using Timers and counters
	2 ND	Ladder diagrams for following (i) DOL starter and STAR-DELTA starter (ii) Stair case lighting (iii) Traffic light Control (iv) Temperature Controller
	3 RD	Special control systems- Basics DCS & SCADA systems
	4 th	Computer Control–Data Acquisition, Direct Digital Control System (Basics only)


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