

Discipline :- ELECTRICAL	Semester:- 5th	Name of the Teaching Faculty:- BISWANATH PRATAP SINGH
ENTREPRENEURSHIP and MANAGEMENT & SMART TECHNOLOGY	No of Days/per Week Class Allotted :- 04	Semester From:- 14.07.2025 To:- 15.11.2025 No of Weeks:- 18
Week	Class Day	Theory
1st	1st	1. Entrepreneurship Concept / Meaning of Entrepreneurship ,
	2nd	Need of Entrepreneurship , Characteristics
	3rd	Quality and Types of Entrepreneur, Functions,
	4th	Barriers of entrepreneurship
2nd	1st	Entrepreneur Vs Manager
	2nd	Forms of Business Ownership ; Sole proprietorship, partnership forms and others
	3rd	Types of industries, Concept of start-ups
	4th	Entrepreneurial support agencies at National , State , District Level (sources): DIC , NSIC, OSIC, SIDBI, NABARD , Commercial Banks , KVIC etc
3rd	1st	Technology business incubators (TBI) and Science and Technology Entrepreneur Parks
	2nd	2. Market Survey and Opportunity Identification (Business Planning) Business planning
	3rd	SSI, Ancillary Units , Tiny Units , Service sector Units
	4th	Time schedule plan , Agencies to be contacted for project Implementation
4th	1st	Assessment of Demand and Supply
	2nd	Potential areas of Growth
	3rd	Identifying Business Opportunity
	4th	Final product selection
5th	1st	3. Project report Preparation Preliminary project report
	2nd	Detailed project report
	3rd	Techno economic feasibility
	4th	Project viability
6th	1st	4. Management Principles Definitions of management
	2nd	Principles of management
	3rd	Functions of management (planning, organizing staffing, directing and controlling etc.)
	4th	Level of Management in an Organisation
7th	1st	5. Functional Areas of management a) Production management->Functions , activities , Productivity
	2nd	Quality control , Production planning and control
	3rd	b) Inventory Management

		Need for Inventory management Model/ Techniques of inventory management
8 th	4 th	
	1 st	c)Financial management Functions of financial management , management of working capital, Costing (only concept) ,Break even analysis
	2 nd	Brief idea about accounting Terminologies: Book Keeping , Jourrnal entry ,Petty Cash book , P & L Accounts, Balance Sheets (only concepts)
	3 rd	d)Marketing Management Concept of Marketing and Marketing Management Marketing Techniques (only concept)
9 th	4 th	Concept of 4P s (price ,place ,product ,promotion)
	1 st	e)Human Resource Management Function of Personnel Management, Man power planning ,
	2 nd	Recruitment ,Sources of manpower ,Selection of manpower , Selection process , Method of Testing ,
	3 rd	Methods of Training & Development , Payment of Wages
10 th	4 th	6. Leadership and Motivation a)Leadership Definition and Need/ Importance
	1 st	Qualities and Functions of a leader
	2 nd	Manager Vs Leader
	3 rd	Style of leadership (Autocratic , Democratic , Participative)
11 th	4 th	b)Motivation Definition and Characteristics, Importance of motivation
	1 st	Factors affecting motivation
	2 nd	Theories of motivation (Maslaw)
	3 rd	Methods of improving Motivation
12 th	4 th	Importance of Communication in Business
	1 st	7. Work Culture , TQM & Safety Types and Barriers of Communication
	2 nd	Human relationship and Performance in Organization
	3 rd	Relation with Peers , Superiors and Subordinates
13 th	4 th	TQM concepts: Quality policy , Quality Management , Quality system
	1 st	Accidents and safety , causes and preventive measures
	2 nd	General safety Rules, Personal Protection Equipment (PPE)
	3 rd	8. Legislation Intellectual Property Rights (IPR)
14 th	4 th	Patents, Trademarks, Copyrights
	1 st	Features of factories Act 1948with amendment(only salient point)
	2 nd	Features of Payment of Wages Act 1936(only salient point)
	3 rd	9. Smart Technology

		Concept of IOT ,How IOT works
	4 th	Components of IOT
15 th	1 st	Characteristics of IOT ,Categories of IOT
	2 nd	Application of IOT – Smart cities ,Smart transportation
	3 rd	Smart Home , Smart Healthcare Smart industry
	4 th	Smart Agriculture, Smart Energy Managementetc
16th	1 st	EXTRA CLASSES
	2 nd	EXTRA CLASSES
	3 rd	EXTRA CLASSES
	4 th	EXTRA CLASSES
17th	1 st	EXTRA CLASSES
	2 nd	EXTRA CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	DOUBT CLEARING CLASSES
18th	1 st	DOUBT CLEARING CLASSES
	2 nd	DOUBT CLEARING CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	DOUBT CLEARING CLASSES

B/18
11/17/2028
Teaching Faculty

XoWp
HOD,EE
11/07/2028

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11/07/2028
Academic Coordinator

<p>Discipline:- Electrical Engineering</p> <p>Subject:- Energy conversion -II</p> <p>Semester:- 5th</p> <p>No. of days/ per week class allotted:-4</p> <p>Week</p> <p>Class day</p>		
		<p>Name of the teaching faculty:-PRABIAT RASHMI MALLIK</p> <p>Semester from:- 14.07.2025 To:- 15.11.2025</p> <p>No. of weeks:18</p>
		Theory
		<p>1. ALTERNATOR:</p> <p>1.1. Types of alternator and their constructional features</p> <p>1.2. Basic working principle of alternator and the relation between speed and frequency</p> <p>1.3. Terminology in armature winding and expressions for winding factors (Pitch factor, Distribution factor).</p> <p>1.4. Explain harmonics, its causes and impact on winding factor.</p>
		<p>1.5. E.M.F equation of alternator. (Solve numerical problems).</p>
		<p>1.6. Explain Armature reaction and its effect on emf at different power factor of load.</p>
		<p>1.6. Explain Armature reaction and its effect on emf at different power factor of load.</p>
		<p>1.7. The vector diagram of loaded alternator. (Solve numerical problems)</p>
		<p>1.7. The vector diagram of loaded alternator. (Solve numerical problems)</p>
		<p>1.8. Testing of alternator (Solve numerical problems) 1.8.1. Open circuit test.</p>
		<p>1.8.2. Short circuit test</p>
		<p>1.9. Determination of voltage regulation of Alternator by direct loading and synchronous impedance method. (Solve numerical problems)</p>
		<p>1.10. Parallel operation of alternator using synchro-scope and dark & bright lamp method</p>
		<p>1.11. Explain distribution of load by parallel connected alternators.</p>
		<p>2. SYNCHRONOUS MOTOR:</p>
		<p>2.1. Constructional feature of Synchronous Motor.</p>
		<p>2.2. Principles of operation, concept of load angle</p>
		<p>2.3. Derive torque, power developed.</p>
		<p>2.4. Effect of varying load with constant excitation</p>
		<p>2.5. Effect of varying excitation with constant load.</p>
		<p>2.6. Power angle characteristics of cylindrical rotor motor</p>
		<p>2.7. Explain effect of excitation on Armature current and power factor.</p>
		<p>2.8. Hunting in Synchronous Motor</p>
		<p>2.9. Function of Damper Bars in synchronous motor and generator.</p>
		<p>2.10. Describe method of starting of Synchronous motor.</p>
		<p>2.10. Describe method of starting of Synchronous motor</p>
		<p>2.11. State application of synchronous moto</p>

	3rd	3. THREE PHASE INDUCTION MOTOR: 3.1. Production of rotating magnetic field.
	4th	3.2. Constructional feature of Squirrel cage and Slip ring induction motors. 3.3. Working principles of operation of 3-phase Induction motor..
7th	1st	3.4. Define slip speed, slip and establish the relation of slip with rotor quantities
	2nd	3.5. Derive expression for torque during starting and running conditions and derive conditions for maximum torque. (solve numerical problems)
	3rd	3.5. Derive expression for torque during starting and running conditions and derive conditions for maximum torque. (solve numerical problems)
	4th	3.6. Torque-slip characteristics 3.7. Derive relation between full load torque and starting torque etc. (solve numerical problems)
8th	1st	3.8. Establish the relations between Rotor Copper loss, Rotor output and Gross Torque and relationship of slip with rotor copper loss. (solve numerical problems)
	2nd	3.9. Methods of starting and different types of starters used for three phase Induction motor.
	3rd	3.10. Explain speed control by Voltage Control, Rotor resistance control, Pole changing, frequency control methods
	4th	3.11. Plugging as applicable to three phase induction motor
9th	1st	3.12. Describe different types of motor enclosures.
	2nd	3.13. Explain principle of Induction Generator and state its applications
	3rd	4. SINGLE PHASE INDUCTION MOTOR: 4.1. Explain Ferrari's principle.
	4th	4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase induction motor.
10th	1st	4.3. Explain Working principle, Torque speed characteristics, performance characteristics and application of following single phase motors 4.3.1. Split phase motor.
	2nd	4.3.2. Capacitor Start motor.
	3rd	4.3.3. Capacitor start, capacitor run motor
	4th	
11th	1st	

	2nd	4.3.4. Permanent capacitor type motor.
	3rd	4.3.5. Shaded pole motor
	4th	4.4. Explain the method to change the direction of rotation of above motors.
12th	1st	5. COMMUTATOR MOTORS: 5.1. Construction, working principle of single phase series motor
	2nd	5.1. Running characteristic and application of single phase series motor
	3rd	5.2. Construction of Universal motors
	4th	5.2. working principle and application of Universal motors
	1st	5.3. Working principle of Repulsion start Motor
13th	2nd	5.3. Working principle of Repulsion start Induction run motor, Repulsion Induction motor.
	3rd	6. SPECIAL ELECTRICAL MACHINE: 6.1. Principle of Stepper motor.
	4th	6.2. Classification of Stepper motor.
	1st	6.3. Principle of variable reluctance stepper motor.
14th	2nd	6.4. Principle of Permanent magnet stepper motor
	3rd	6.5. Principle of hybrid stepper motor 6.6. Applications of Stepper motor.
	4th	7. THREE PHASE TRANSFORMERS: 7.1. Explain Grouping of winding, Advantages.
	1st	7.2. Explain parallel operation of the three phase transformers.
15th	2nd	7.3. Explain tap changer (On load tap changing).
	3rd	7.4 Explain Off load tap changing
	4th	7.4. Maintenance Schedule of Power Transformers.
	1st	DOUBT CLEARING CLASSES
16th	2 nd	DOUBT CLEARING CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	DOUBT CLEARING CLASSES
	1st	Problem Solving Classes
17th	2 nd	DOUBT CLEARING CLASSES
	3 rd	Problem Solving Classes
	4 th	EXTRA CLASSES
	1st	EXTRA CLASSES
18th	2 nd	EXTRA CLASSES

	3 rd 4 th	EXTRA CLASSES EXTRA CLASSES
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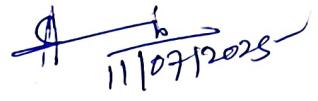
Teaching Faculty


11/07/2025

HOD,EE


11/07/2025

Academic Coordinator


11/07/2025

Discipline: ELECTRICAL ENGINEERING	Semester :5th	Name of the Teaching Faculty: SOMA DAS
Subject: DE&MP	No. of days/per week class allotted:05	Semester From date : <u>02.08.2025</u> To:- <u>15.11.2025</u>
Week	Class Day	Theory Topics
1 ST	1 ST	Binary, Octal, Hexadecimal number systems and compare with Decimal system.
	2 ND	Binary addition, subtraction, Multiplication and Division.
	3 RD	1's complement and 2's complement numbers for a binary number
	4 th	Subtraction of binary numbers in 2's complement method.
	5 th	Use of weighted and Un-weighted codes & write Binary equivalent number for a number in 8421, Excess-3 and Gray Code and vice-versa
2 ND	1 ST	Importance of parity Bit.
	2 ND	Logic Gates: AND, OR, NOT, NAND, NOR and EX-OR gates with truth table. 1.8 Realize
	3 RD	Realize AND, OR, NOT operations using NAND, NOR gates
	4 th	Different postulates and De-Morgan's theorems in Boolean algebra
	5 th	Use Of Boolean Algebra For Simplification Of Logic Expression
3 RD	1 ST	Karnaugh Map For 2,3,4 Variable, Simplification Of SOP And POS Logic Expression Using K-Map.
	2 ND	Give the concept of combinational logic circuits
	3 RD	Half adder circuit and verify its functionality using truth table
	4 th	Realize a Half-adder using NAND gates only and NOR gates only
	5 th	Full adder circuit and explain its operation with truth table
4 TH	1 ST	Realize full-adder using two Half-adders and an OR – gate and write truth table
	2 ND	Full subtractor circuit and explain its operation with truth table.
	3 RD	Operation of 4 X 1 Multiplexers and 1 X 4 demultiplexer
	4 th	Working of Binary-Decimal Encoder & 3 X 8 Decoder
	5 th	Working of Two bit magnitude comparator
5 TH	1 ST	Give the idea of Sequential logic circuits
	2 ND	State the necessity of clock and give the concept of level clocking and edge triggering
	3 RD	Clocked SR flip flop with preset and clear inputs.
	4 th	Construct level clocked JK flip flop using S-R flip-flop and explain with truth table

	5 th	Concept of race around condition and study of master slave JK flip flop.
6 TH	1 ST	Give the truth tables of edge triggered D and T flip flops and draw their symbols.
	2 ND	Applications of flip flops.
	3 RD	Define modulus of a counter 4-bit asynchronous counter
	4 TH	4-bit asynchronous counter's timing diagram
	5 TH	Asynchronous decade counter
7 TH	1 ST	4-bit synchronous counter.
	2 ND	Distinguish between synchronous and asynchronous counters
	4 TH	State the need for a Register and list the four types of registers.
	5 TH	WORKING OF PISO, PIPO Register with truth table using flip flop
8 TH	1 ST	Introduction to Microprocessors
	2 ND	Evolution of digital computer, Microprocessors
	3 RD	Basics of CPU and its block diagram
	4 TH	Basics of Memory, different types of Memory
	5 TH	Buses- Data, Address and Control Bus
9 TH	1 ST	Architecture of Intel 8085A Microprocessor
	2 ND	Description of each block in Architecture
	3 RD	Status Flag concept
	4 TH	Status flag with examples
	5 TH	Stack, Stack pointer & stack top
10 TH	1 ST	Pin diagram
	2 ND	Grouping of pins
	3 RD	Description of each groups briefly
	4 TH	Relation between IO/Memory and read-write operation
	5 TH	Reset instruction
11 TH	1 ST	Address and Address-Data instruction
	2 ND	Interrupts
	3 RD	Opcode & Operand
	4 TH	one byte, two byte & three byte instruction
	5 TH	Differentiate between one byte, two byte & three byte instruction with example.
12 TH	1 ST	Instruction set of 8085
	2 ND	Instruction set of 8085 example
	3 RD	Addressing mode
	4 TH	Fetch Cycle, Machine Cycle, Instruction Cycle, T-State
	5 TH	Using of Fetch Cycle, Machine Cycle, Instruction Cycle, T-State in Timing Diagram

13 RD	1 ST	Timing Diagram for memory read, memory write
	2 ND	Timing Diagram for I/O read, I/O write
	3 RD	Timing Diagram for 8085 instruction
	4 th	Timing Diagram for 8085 instruction with examples
	5 th	Counter and time delay
14 TH	1 ST	Simple assembly language programming of 8085
	2 ND	Simple assembly language programming of 8085
	3 RD	Introduction to interfacing and support chips
	4 th	Basic Interfacing Concepts
	5 th	Memory mapping & I/O mapping
15 TH	1 ST	Functional block diagram and description of each block of Programmable peripheral interface Intel 8255
	2 ND	Description of each block of Programmable peripheral interface Intel 8255
	3 RD	Application using 8255: Seven segment LED display
	4 th	Application using 8255: Square wave generator
	5 th	Application using 8255: Traffic light Controller

Teaching Faculty

Prashant
09/09/2025

Palash
08/08/25
HOD, EE

08/08/2025
Academic Coordinator

Discipline:- Electrical Engineering	Semester:- 5th	Name of the teaching faculty:-PRABHAT RASHMI MALLIK
Subject:- Utilization Of Electrical Energy And Traction	No. of days/ per week class allotted:-4	Semester from:- <u>14.07.2025</u> To:- <u>15.11.2025</u> No. of weeks:18
Week	Class day	Theory
1 st	1st	1. ELECTROLYTIC PROCESS 1.1 Definition and Basic principle of Electro Deposition.
	2nd	1.2 Important terms regarding electrolysis
	3rd	1.3 Faradays Laws of Electrolysis. 1.4 Definitions of current efficiency, Energy efficiency
	4th	1.5 Principle of Electro Deposition.
2 nd	1st	1.6 Factors affecting the amount of Electro Deposition
	2nd	1.7 Factors governing the electro deposition.
	3rd	1.8 State simple example of extraction of metals.
	4th	1.9 Application of Electrolysis.
3rd	1st	ELECTRICAL HEATING 2.1. Advantages of electrical heating. 2.2. Explain mode of heat transfer and Stephen's Law.
	2nd	2.3. Discuss principle of Resistance heating. Direct Resistance heating. Indirect Resistance heating
	3rd	2.4. Explain working principle of direct arc furnace and indirect arc furnace.
	4th	2.5. Principle of Induction heating
4th	1st	2.5.1 Working principle of direct core type, vertical core type and indirect core type Induction furnace.
	2nd	2.5.2. Principle of coreless induction furnace and skin effect.
	3rd	2.6. Principle of dielectric heating and its application
	4th	2.7. Principle of Microwave heating and its application.
5th	1st	PRINCIPLES OF ARC WELDING 3.1 Explain principle of arc welding.
	2nd	3.2 Discuss D. C. & A. C. arc phenomena
	3rd	3.3 D.C. & A. C. arc welding plants of single and multi-operation type.
		3.3 D.C. & A. C. arc welding plants of single and multi-operation type.
6th	1st	3.4 Types of arc welding
	2nd	3.5 Explain principles of resistance welding.
	3rd	3.6 Descriptive study of different resistance welding methods.
	4th	3.6 Descriptive study of different resistance welding methods.
7th	1st	4. ILLUMINATION

		4 . 1 Nature of Radiation and its spectrum.
	2nd	4 . 2 Terms used in Illuminations. i. Luminous intensity ii. Lumen iii. Intensity of illumination iv. MHCP v. MSCP vi. MHSCP vii. Brightness viii. Solid angle ix. Luminous efficiency
	3rd	4 . 3 Explain the inverse square law and the cosine law
	4th	4 . 4 Explain polar curves.
8th	1st	4 . 5 Describe light distribution and control. Explain related definitions like maintenance factor and depreciation factors.
	2nd	4 . 6 Design simple lighting schemes and depreciation factor.
	3rd	4. 7 Constructional feature and working of Filament lamps, effect of variation of voltage on working of filament lamps.
9th	4th	4 . 8 Explain Discharge lamps. 4 . 9 State Basic idea about excitation in gas discharge lamps. 4 . 10 State constructional features and operation of: - Fluorescent lamp. (PL and PLL Lamps)
	1st	4.11 Sodium Vapor lamp
	2nd	4.12 High Pressure Mercury vapor lamp
	3rd	4.13 Neon sign lamp
	4th	4.14 High Lumen output & low consumption fluorescent lamp
10th	1st	INDUSTRIAL DRIVES 5 . 1 State group and individual drive.
	2nd	5 . 2 Method of choice of electric drives.
	3rd	5 . 3 Explain starting and running characteristics of DC and AC motor.
	4th	5 . 3 Explain starting and running characteristics of DC and AC motor.
11th	1st	5 . 3 Explain starting and running characteristics of DC and AC motor.
	2nd	5 . 3 Explain starting and running characteristics of DC and AC motor.
	3rd	5 . 4 State Application of : 5.4.1 DC motor
	4th	5.4.2 3-phase induction motor

12th	1st	5.4.3 3-phase synchronous motors
	2nd	5.4.4 Single phase induction ,series motor, universal motor & repulsion motor
	3rd	ELECTRIC TRACTION 6. 1. Explain system of traction
	4th	6. 1. Explain system of traction
13th	1st	6. 2. System of Track electrification
	2nd	6. 2. System of Track electrification
	3rd	6. 3. Running Characteristics of DC and AC traction motor
	4th	6. 3. Running Characteristics of DC and AC traction motor
14th	1st	6. 4. Explain control of motor 6.4.1 Tapped field control
	2nd	6. 4. 2 Rheostatic control
	3rd	. 6.4.3 Series parallel control
	4th	6. 4.4 Multi-unit control
15th	1st	6.4.5 Explain control of Metadyne control
	2nd	6. 5. Explain Braking of the following types. 6.5.1 Regenerative Braking
	3rd	6.5.2 Braking with 1-phase series motor
	4th	6.5.3 Magnetic Braking
16th	1st	DOUBT CLEARING CLASSES
	2 nd	DOUBT CLEARING CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	DOUBT CLEARING CLASSES
17th	1st	DOUBT CLEARING CLASSES
	2 nd	DOUBT CLEARING CLASSES
	3 rd	DOUBT CLEARING CLASSES
	4 th	EXTRA CLASSES
18th	1st	EXTRA CLASSES
	2 nd	EXTRA CLASSES
	3 rd	EXTRA CLASSES
	4 th	EXTRA CLASSES

Teaching Faculty

Draft No
11/07/2025

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Academic Coordinator

S. f
11/07/2025

Discipline: ELECTRICAL ENGINEERING	Semester :5th	Name of the Teaching Faculty: PRATIK DAS & PREETINANDA MISRA
Subject: PE&PLC	No. of days/per week class allotted:04	Semester From date : <u>09.09.2025</u> To:- <u>15.11.2025</u>
Week	Class Day	Theory Topics
1 ST	1 ST	Construction, Operation, V-I characteristics & application of power diode, SCR, DIAC, TRIAC, Power MOSFET, GTO & IGBT
	2 ND	Two transistor analogy of SCR. Gate characteristics of SCR.
	3 RD	Switching characteristic of SCR during turn on and turn off.
	4 th	Turn on methods of SCR.
2 ND	1 ST	Turn off methods of SCR (Line commutation and Forced commutation) - Load Commutation, Resonant pulse commutation
	2 ND	Voltage and Current ratings of SCR.
	3 RD	Protection of SCR - Over voltage protection, Over current protection, Gate protection
	4 th	Firing Circuits- General layout diagram of firing circuit, R firing circuits, R-C firing circuit, UJT pulse trigger circuit
3 RD	1 ST	Synchronous triggering (Ramp Triggering) Design of Snubber Circuits
	2 ND	Controlled rectifiers Techniques (Phase Angle, Extinction Angle control) Single quadrant semi converter
	3 RD	Two quadrant full converter and dual Converter Working of single-phase half wave controlled converter with Resistive and R-L loads.
	4 th	Understand need of freewheeling diode. Working of single phase fully controlled converter with resistive and R-L loads
4 TH	1 ST	Working of three-phase half wave controlled converter with Resistive load
	2 ND	Working of three phase fully controlled converter with resistive load.
	3 RD	Working of single phase AC regulator Working principle of step up & step down chopper.
	4 th	Control modes of chopper Operation of chopper in all four quadrants.
5 TH	1 ST	Classify inverters. Explain the working of series inverter.
	2 ND	Explain the working of parallel inverter Explain the working of single-phase bridge inverter.
	3 RD	Explain the basic principle of Cyclo-converter.

	4 th	Explain the working of single-phase step up & step down Cyclo-converter. Applications of Cyclo-converter.
6 TH	1 ST	List applications of power electronic circuits. List the factors affecting the speed of DC Motors.
	2 ND	Speed control for DC Shunt motor using converter.
	3 RD	Speed control for DC Shunt motor using chopper. List the factors affecting speed of the AC Motors.
	4 th	Speed control of Induction Motor by using AC voltage regulator.
7 TH	1 ST	Speed control of induction motor by using converters and inverters (V/F control)
	2 ND	Working of UPS with block diagram
	3 RD	Battery charger circuit using SCR with the help of a diagram.
	4 th	Basic Switched mode power supply (SMPS) - explain its working & applications
8 TH	1 ST	Introduction of Programmable Logic Controller(PLC)
	2 ND	Advantages of PLC Different parts of PLC by drawing the Block diagram
	3 RD	purpose of each part of PLC In the Block diagram
	4 th	Different parts of PLC by drawing the Block diagram and purpose of each part of PLC. 5.4 Applications of PLC
9 TH	1 ST	Description of contacts and coils in the following states i)Normally open ii) Normally closed iii) Energized output
	2 ND	iv)latched Output v) branching PLC Instruction set
	3 RD	Ladder diagrams for i) AND gate ii) OR gate and iii) NOT gate. Ladder diagrams for combination circuits using NAND,NOR, AND, OR and NOT
	4 th	Timers-i)T ON ii) T OFF and iii)Retentive timer
10 TH	1 ST	Counters-CTU, CTD Ladder diagrams using Timers and counters
	2 ND	Ladder diagrams for following (i) DOL starter and STAR-DELTA starter (ii) Stair case lighting (iii) Traffic light Control (iv) Temperature Controller
	3 RD	Special control systems- Basics DCS & SCADA systems
	4 th	Computer Control-Data Acquisition, Direct Digital Control System (Basics only)

Pooja Desai
09.09.25 09.09.2025

Teaching Faculty

S. D. Patel
09.09.25
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09/09/2025
Academic Coordinator